

# **GENETIC ALGORITHMS IN MANUFACTURING SYSTEMS DESIGN**

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**METHODOLOGY** 

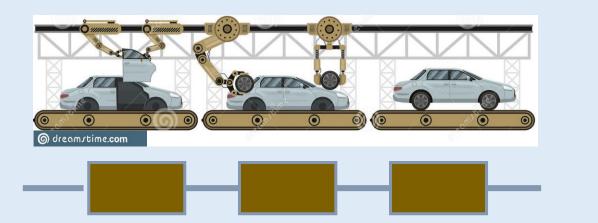


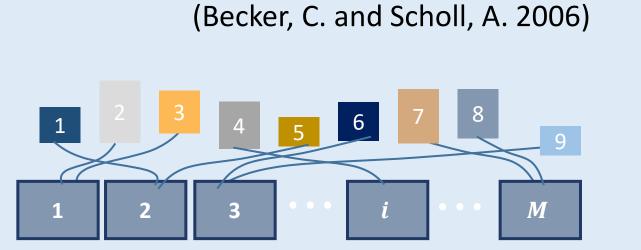
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#### BACKGROUND

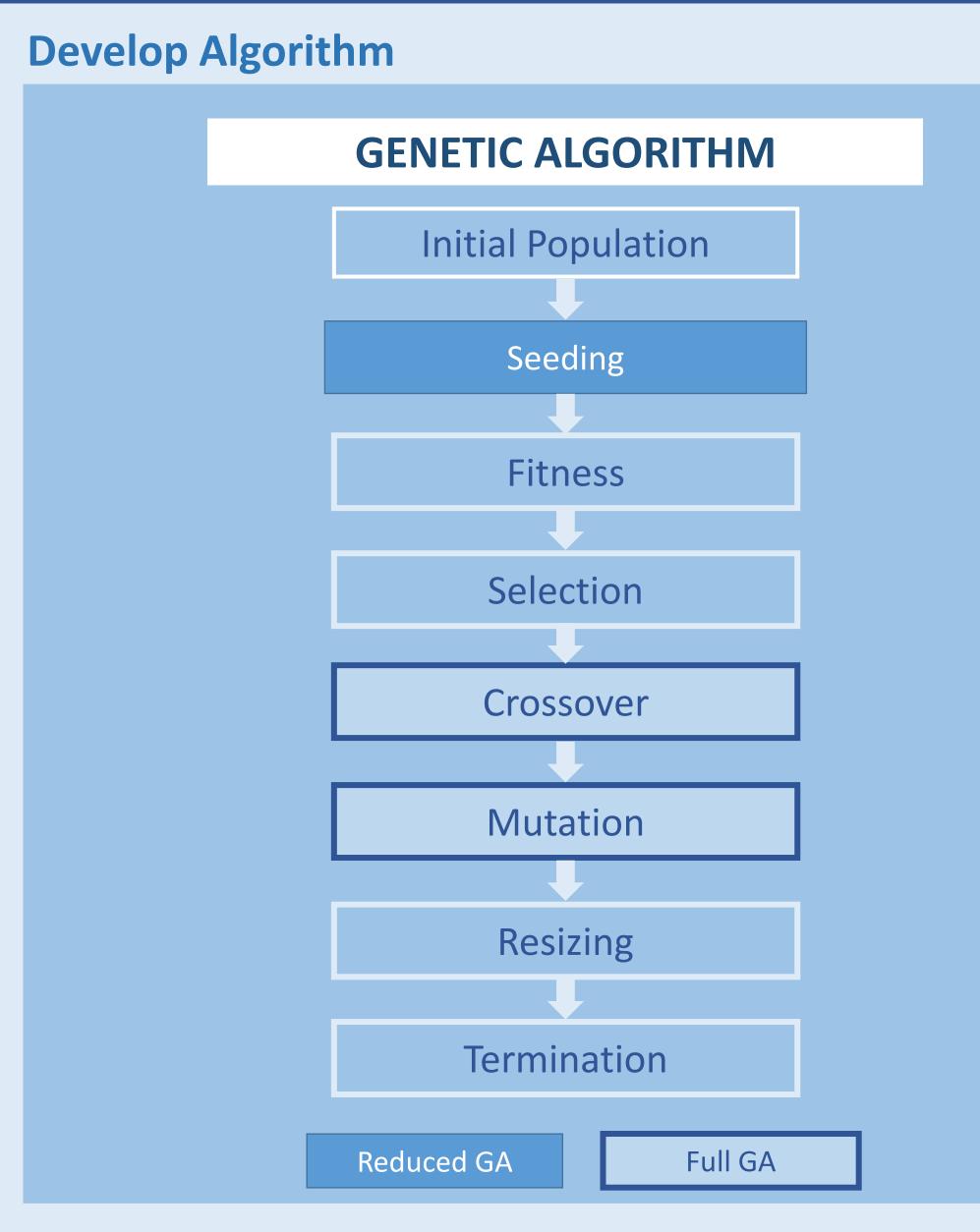
#### Manufacturing Systems

- Manufacturing systems design begins with the solution of the assembly line balancing problem
- The simple assembly line balancing problem (SALBP) is used to determine the assignment of tasks to workstations
- The Type I simple assembly line balancing problem (SALBP-1) minimizes the number of workstations for a given cycle time, and the Type II does the converse
- SALBP-1 and SALBP-2 are NP-hard





(Holland, J. 1975)



## **Reduced GA**

#### Convergence Times

The experimental results were in close agreement with the analytical solutions for the Reduced GA

RESULTS

- Maximum convergence times were closer to the predicted average convergence times
- RWS performed the best and SUS the worst

	Predicted			Example 1			Example 2			Example 3			Example 4		
p <sub>s</sub>	$G^L$	$G^{U}$	Ē	$G^L$	$G^{U}$	Ē	$\boldsymbol{G}^{L}$	$G^{U}$	Ē	$G^L$	$G^{U}$	Ē	$G^L$	$G^{\overline{U}}$	Ē
		ES													
0.25	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0	6.0
0.50	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0
0.75	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0
1.00	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0	5.0
	RWS														
0.25	_	_	-	5.0	9.0	5.7	5.0	6.0	5.2	5.0	10.0	6.0	5.0	7.0	5.5
0.50	-	-	-	3.0	5.0	3.7	3.0	4.0	3.3	3.0	6.0	3.8	3.0	5.0	3.5
0.75	-	_		3.0	4.0	3.3	3.0	3.0	3.0	3.0	4.0	3.3	3.0	4.0	3.2
1.00	I	-	-	2.0	4.0	2.5	2.0	3.0	2.3	2.0	4.0	2.7	2.0	3.0	2.5
	SUS														
-	5.0	451.0	5.0	5.0	8.0	5.5	5.0	8.0	5.5	5.0	9.0	5.5	5.0	9.0	5.5
	TS														
0.25	5.0	451.0	12.0	7.0	10.0	8.2	7.0	10.0	8.3	7.0	10.0	8.2	7.0	10.0	8.3
0.50	3.0	451.0	7.0	5.0	6.0	5.1	5.0	6.0	5.1	5.0	6.0	5.1	5.0	6.0	5.1
0.75	3.0	451.0	6.0	4.0	5.0	4.1	4.0	5.0	4.0	4.0	5.0	4.1	4.0	5.0	4.1
1.00	2.0	451.0	5.0	3.0	4.0	4.0	3.0	4.0	4.0	3.0	4.0	4.0	3.0	4.0	4.0

#### **Genetic Algorithms**

- Genetic algorithms (GAs) are evolutionary algorithms based on natural selection
- The performance of GA populations improve as generations evolve through the use of genetic operators

Task Sequence Position of Task in Sequence

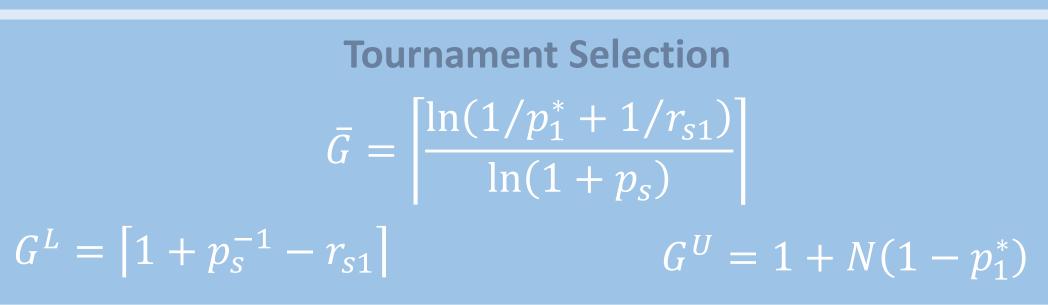
#### **GA Selection Methods**

- Selection methods are used to select members of the population for mating
- A selection method that is too aggressive causes early convergence of a GA, and one that is not sufficiently aggressive converges too slowly
- There are two main types of Selection Methods
- Proportionate Selection
- Ordinal Selection

(Sastry, K., Goldberg, D. and Kendall, G., 2005)

2. Develop Test Parameters No. of Generations to Convergence

**Elitist Selection**  $G = \left[1 - \log_2 r_{s_1}\right] + \left|\frac{1}{p_s} - r_{s_1} 2^{\left[1 - \log_2 r_{s_1}\right] - 1}\right| \quad 0 < r_{s_1} \le 1$  $G = \left[1 + p_s^{-1} - r_{s1}\right]$  $r_{s1} \geq 1$ 



#### **Roulette Wheel Selection**

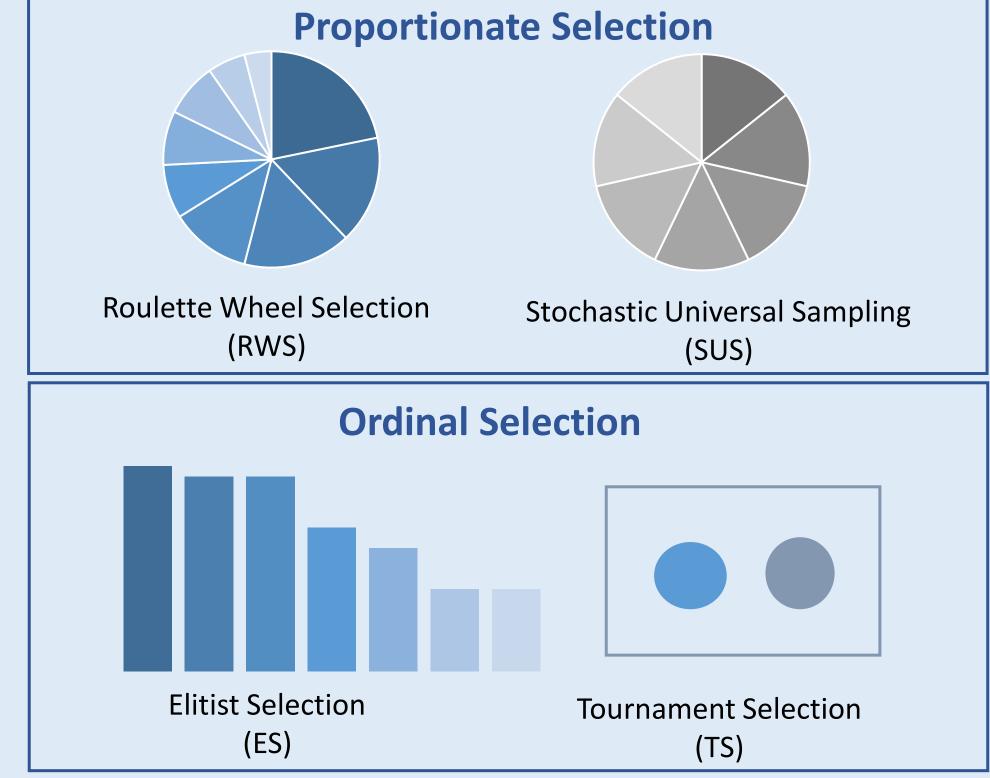
#### > Other Parameters

- Trends in the results were consistent across the correlation parameter,  $d_
  ho$  , the generational growth rate,  $ar{\phi}$  , and generational diversity,  $\beta_{\Delta}$
- The ranking of Selection Methods across all parameters was as follows

1	2	3	4
RWS	TS	ES	SUS

**Full GA** 

- Test Parameters
  - The results of the Full GA were not consistent with those of the reduced GA
  - Convergence times varied between SALBP-1 and SALBP-2, and also with the size of the problem



### **AIM & OBJECTIVES**

To investigate the influence that GA selection methods have on the solution of the SALBP

# **Objectives**

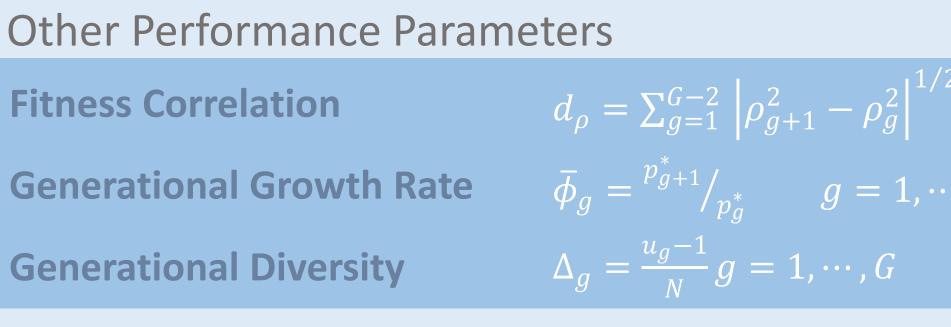
- To compare the performances of ES, RWS, TS, and SUS in the solution of the SALBP-1 and SALBP-2
- To determine the effects that other GA parameters, viz. population

$G^{L} = \left[1 + p_{s}^{-1} - r_{s1}\right]$	$G^{U}$	$= 1 + N(1 - p_1^*)$

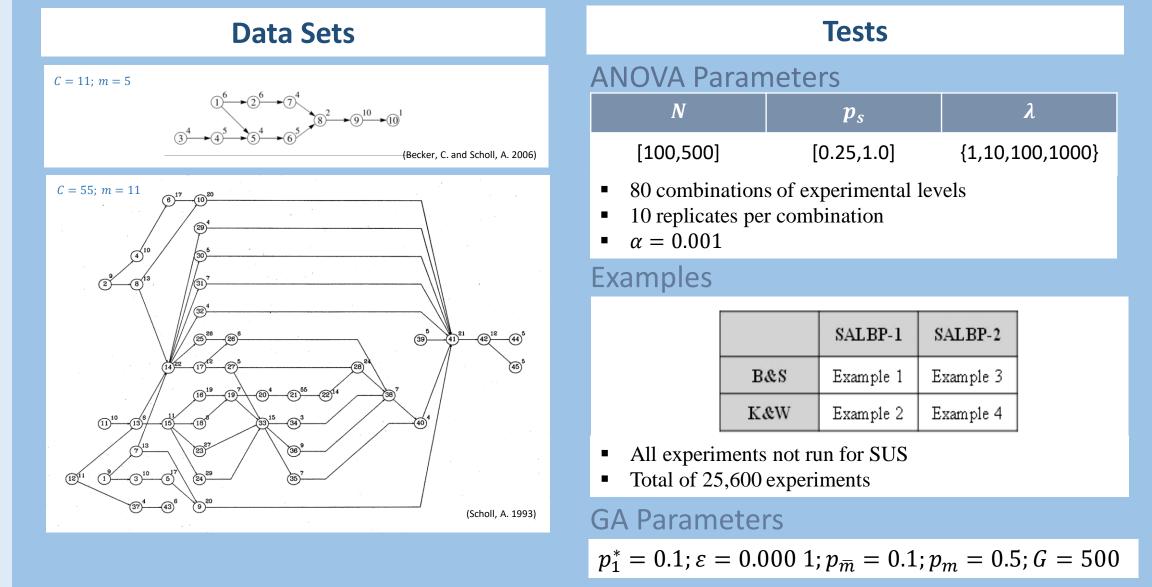
Stochastic Universal Sampling  

$$\bar{G} = [1 - \log_2 2p_1^*] + 2 \left[ 1 - p_1^{* \lceil 1 - \log_2 2p_1^* \rceil} \right] \quad 0 < 2p_1^* < \bar{G} = 1 + \lceil 2(1 - p_1^*) \rceil 2p_1^* \ge 1$$

 $g = 1, \cdots, G - 1$ 



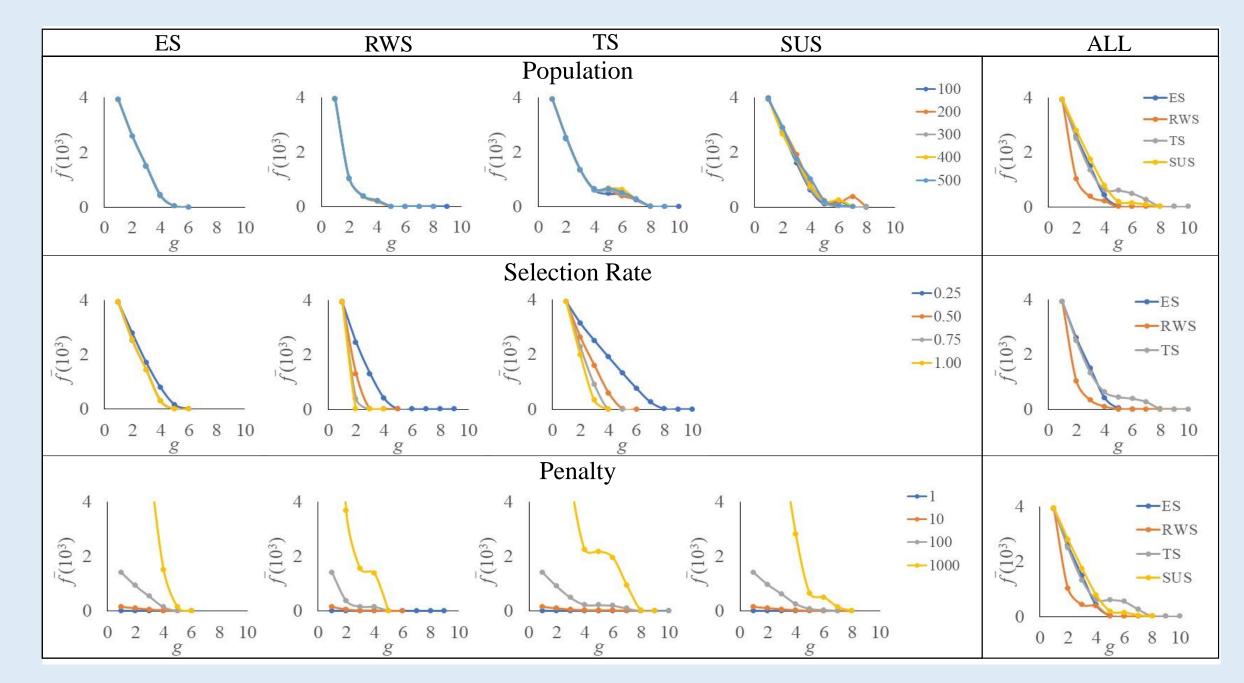
**Design Experiments** 3.



The observation for convergence times was consistent across all parameters

#### **GA** Parameters

- Selection Methods were unaffected by population size
- The magnitude of penalty in the fitness function had the largest effect on Selection Methods



#### REFERENCES

Scholl, A., 1993, "Data of Assembly Line Balancing Problems," Institut fur Betriebswirtschaftslehre, Technische Universitat Darmstadt, Darmstadt, Germany.

Holland, J. H., 1975, "Adaptation in Natural and Artificial Systems," The University of Michigan Press, Ann Arbor, Michigan, USA.

#### size, selection rate, and penalty have on the performance of GAs



